EE6612 MICROPROCESSOR AND MICROCONTROLLER LABORATORY 1





Dharmapuri – 636 703

# LAB MANUAL

**Regulation** :

: 2013

Branch

: *B.E. -* EEE

Year & Semester : III Year / VI Semester

## EE6612-MICROPROCESSOR AND MICROCONTROLLER LAB



## **ANNA UNIVERSITY: CHENNAI**

## **REGULATION - 2013**

## **SYLLABUS**

## EE6612 MICROPROCESSOR AND MICROCONTROLLER LABORATORY

## **OBJECTIVES:**

To provide training on programming of microprocessors and microcontrollers and understand the interface requirements.

## **LIST OF EXPERIMENTS:**

- 1. Simple arithmetic operations: addition / subtraction / multiplication / division.
- 2. Programming with control instructions:
  - (i) Ascending / Descending order, Maximum / Minimum of numbers
  - (ii) Programs using Rotate instructions
  - (iii)Hex / ASCII / BCD code conversions.
- 3. Interface Experiments: with 8085

(i) A/D Interfacing. & D/A Interfacing.

- 4. Traffic light controller.
- 5. I/O Port / Serial communication
- 6. Programming Practices with Simulators/Emulators/open source
- 7. Read a key, interface display
- 8. Demonstration of basic instructions with 8051 Micro controller execution, including:
  - (i) Conditional jumps, looping
  - (ii) Calling subroutines.
- 9. Programming I/O Port 8051
  - (i) study on interface with A/D & D/A
  - (ii) study on interface with DC & AC motor.
- 10. Mini project development with processors.

#### **TOTAL: 45 PERIODS**

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#### Ex No :1

Date :

## PROGRAM FOR 8 BIT ADDITION USING 8085

#### AIM:

To write an assembly language program for addition of two 8 bit data using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Clear the register **C**
- 2. Initialize the memory pointer to data location.
- 3. Get the first Data from memory Location and move to register A.
- 4. Get the second data from memory location.
- 5. Add first and second data.
- 6. If carry the increment the register **C** by one.
- 7. Store the result to memory location.

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#### **FLOW CHART:** (8 bit Addition)



ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MVI C,00		Clear the "C" Register
		LXI H,9200		Initialize the memory pointer
		MOV A,M		Move the First Data to A Register
		INX H		Increment the memory pointer
		ADD M		Add First and Second Data
		JNC LOOP1		Jump if No Carry to loop1
		INR C		Increment the "C" register by one
	Loop1	STA 9500		Store the Result
		MOV A,C		Move the Carry result to Register "A"
		STA 9501		Store the Carry Result
		HLT		Stop the program

## Input:

Memory location	Data
9200	
9201	

## **Output:**

Memory location	Data
9500	
9501	

## <u>Result :</u>

Thus the addition of two 8 bit data's was executed using the 8085 microprocessor.

#### Ex No : 2

Date :

## PROGRAM FOR 8 BIT SUBTRACTION USING 8085

#### AIM:

To write an assembly language program for subtraction of two 8 bit data using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Clear the register "C"
- 2. Initialize the memory pointer to data location.
- 3. Get the first Data from memory Location and move to register "A".
- 4. Get the second data from memory location.
- 5. Subtract the first and second data.
- 6. If occur carry the increment the register 'c' by one.
- 7. Store the result to memory location.

#### **FLOW CHART:** (8 bit Subtraction)



ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MVI C,00		Clear the "C" Register
		LXI H,9200		Initialize the memory pointer
		MOV A,M		Move the First Data to A Register
		INX H		Increment the memory pointer
		SUB M		Subtract First and Second Data
		JNC LOOP1		Jump if No Carry to loop1
		INR C		Increment the "C" register by one
		СМА		Complement the Accumulator
		ADI 01		Add by one for two's complement
	Loop1	STA 9500		Store the Result
		MOV A,C		Move the Carry result to Register "A"
		STA 9501		Store the Carry Result
		HLT		Stop the program

#### Input:

Memory location	Data
9200	
9201	

## **Output:**

Memory location	Data
9500	
9501	

## **<u>RESULT</u>** :

Thus the subtraction of two numbers was performed using the 8085 microprocessor.

## Exp No : 3 Date :

## **PROGRAM FOR 8 BIT MULTIPLICATION USING 8085**

#### AIM:

To write an assembly language program for multiplication of two 8 bit data using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Clear the register "A"
- 2. Initialize the memory pointer to data location.
- 3. Get the first Data from memory Location and move to register "C".
- 4. Get the second data from memory location.
- 5. Add the Memory Data and A Register.
- 6. Decrement the register 'c' by one
- 7. Check the register "C' is Zero otherwise repeat step 5.
- 8. Store the result to memory location.

#### **PROGRAM**:

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		<i>MVI</i> A,00		Clear the "A" Register
		LXI H,9200		Initialize the memory pointer
		MOV C,M		Move the First Data to C Reg
		INX H		Increment the memory pointer
	Loop1	ADD M		Add First and Second Data
		DCR C		Decrement C register by one
		JNZ LOOP1		Jump if No Zero to loop1
		STA 9500		Store the Result
		HLT		Stop the program

#### **FLOW CHART:** (8 bit Multiplication)



## Input:

Memory location	Data
9200	
9201	

#### **Output:**

Memory location	Data
9500	

#### **<u>RESULT</u>**:

Thus the multiplication of two numbers was performed using the 8085 microprocessor.

## Exp No: 4 Date :

## **PROGRAM FOR 8 BIT DIVISION USING 8085**

#### AIM:

To write an assembly language program for division of two 8 bit data using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Clear the Register "C".
- 2. Initialize the Memory Pointer.
- 3. Get the First Data from memory to Accumulator (Dividend)
- 4. Get the Second Data from memory (Divisor)
- 5. Compare Register "A" and "M"
- 6. If No carry, Subtract Divisor from Dividend [(A)-(M)]
- 7. Increment Register "C" by one.
- 8. Compare Register "A" and "M"
- 9. If No Carry go to step 6
- 10. Store the result to memory location.



ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MVI C,00		Clear the "C" Register
		LXI H,9200		Initialize the memory pointer
		MOV A,M		Move the First Data to A Register
		INX H		Increment the memory pointer
		CMP M		Compare register A and M data's
		JC Loop1		If carry jump to loop1
	Loop2	SUB M		Subtract register A and M Data
		INR C		Increment C register by one
		CMP M		Compare register A and M data's
		JNC Loop2		Jump if No Carry to loop2
		STA 9500		Store the Quotient Result
		MOV A,C		Move register C to A
		STA 9501		Store the Remainder Result
		HLT		Stop the program
	Loop1	<i>MVI</i> A,00		Clear the accumulator
		STA 9500		Store the result
		STA 9501	]	Store the result
		HLT		stop

## Input:

Memory location	Data
9200	
9201	

## **Output:**

Memory location	Data
9500	
9501	

#### **<u>RESULT</u>** :

Thus the division of two numbers was performed using the 8085 microprocessor.

## Exp No : 5 Date :

## LARGEST NUMBER OF PROGRAM IN A GIVEN ARRAY

#### AIM:

To write an assembly language program to find the largest number in a given array using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Initialize the Memory Pointer.
- 2. Load the number of array to B register.
- 3. Move the first data to register A.
- 4. Increment the Memory pointer.
- 5. Compare the register A and M.
- 6. If No carry jump to loop2.
- 7. Move the register M to A.
- 8. Decrement the register B by one.
- 9. Check register B is Zero otherwise go to step 4.
- 10. Store the Largest value to memory location.
- 11. Stop.

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ADDRES S	LABEL	MNEMONICS	OPCOD E	COMMENTS
8000		LXI H,9100		Initialize the memory pointer
		MVI B,04		Load the counter to register B
		MOV A,M		Move the First Data to A Register
	Loop1	INX H		Increment the memory pointer
		CMP M		Compare register A and M datas
		JNC Loop2		If No carry jump to loop2
		MOV A, M		Move register M to A
	LOOP2	DCR B		Decrement B register by one
		CMP M		Compare register A and M data's
		JNZ Loop1		Jump if No Zero to loop1
		STA 9500		Store the Result to memory
		HLT		Stop

## Input:

Memory location	Data
9100	
9101	
9102	
9103	

#### **Output:**

Memory location	Data
9500	

## **RESULT:**

Thus the program to find the largest number in a given array using 8085 microprocessor was executed.

## Exp No : 6 Date :

#### SMALLEST NUMBER OF PROGRAM IN A GIVEN ARRAY

#### AIM:

To write an assembly language program to find the smallest number in a given array using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Initialize the Memory Pointer.
- 2. Load the number of array to B register.
- 3. Move the first data to register A.
- 4. Increment the Memory pointer.
- 5. Compare the register A and M.
- 6. If carry jump to loop2.
- 7. Move the register M to A.
- 8. Decrement the register B by one.
- 9. Check register B is Zero otherwise go to step 4.
- 10. Store the Largest value to memory location.
- 11. Stop.

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#### **FLOWCHART:** (Smallest Number)

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		LXI H,9100		Initialize the memory pointer
		MVI B,04		Load the counter to register B
		MOV A,M		Move the First Data to A Register
	Loop1	INX H		Increment the memory pointer
		CMP M		Compare register A and M
				datas
		JC Loop2		If carry jump to loop2
		MOV A, M		Move register M to A
	Loop2	DCR B		Decrement B register by one
		CMP M		Compare register A and M
				data's
		JNZ Loop1		Jump if No Zero to loop1
		STA 9500		Store the Result to memory
		HLT		Stop

## Input:

## **Output:**

Memory location	Data
9100	
9101	
9102	
9103	

Memory location	Data
9500	

## **RESULT:**

Thus the program to find the smallest number in a given array using 8085 microprocessor was executed.

## Exp No : 7 Date :

#### PROGRAM SORT ASCENDING OREDR IN A GIVEN ARRAY

#### AIM:

To write an assembly language program to sort ascending order in a given array using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Initialize the Memory Pointer.
- 2. Load the number of array to B register.
- 3. Move the first data to register A.
- 4. Increment the Memory pointer.
- 5. Compare the register A and M.
- 6. If carry jump to loop2.
- 7. Move the register M to A.
- 8. Decrement the register B by one.
- 9. Check register B is Zero otherwise go to step 4.
- 10. Store the Largest value to memory location.
- 11. Stop.

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#### **FOWCHART:** (Ascending Order)

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MVI B,09		Load the counter to register B
	L3	LXI H,9100		Initialize the memory pointer
		MVI C,09		Load the counter value
	L2	MOV A,M		Move the First Data to A Register
		INX H		Increment the memory pointer
		CMP M		Compare register A and M data's
		JC L1		If carry jump to loop1
		MOV D, M		Move register M to D
		MOV M,A		Move register M to A
		DCX H		Decrement memory pointer
		MOV M,D		Move register M to D
		INX H		Increment memory pointer
	L1	DCR C		Decrement B register by one
		JNZ L2		Jump if No Zero to loop2
		DCR B		Decrement B register by one
		JNZ L3		Jump if No Zero to loop3
		HLT		Stop

## Input:

Memory location	Data
9100	
9101	
9102	
9103	
9104	
9105	
9106	
9107	
9108	
9109	

## **Output:**

Memory location	Data
9100	
9101	
9102	
9103	
9104	
9105	
9106	
9107	
9108	
9109	

#### **RESULT:**

-

Thus the program of sort the ascending order in given array was executed by using 8085.

Exp No : 8 Date :

#### PROGRAM SORT DESCENDING OREDR IN A GIVEN ARRAY

#### <u>AIM:</u>

To write an assembly language program to sort descending order in a given array using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Initialize the Memory Pointer.
- 2. Load the number of array to B register.
- 3. Move the first data to register A.
- 4. Increment the Memory pointer.
- 5. Compare the register A and M.
- 6. If no carry jump to loop2.
- 7. Move the register M to A.
- 8. Decrement the register B by one.
- 9. Check register B is Zero otherwise go to step 4.
- 10. Store the Largest value to memory location.
- 11. Stop.

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ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MVI B,04		Load the counter to register B
	L3	LXI H,9100		Initialize the memory pointer
		MVI C,04		Load the counter value
	L2	MOV A,M		Move the First Data to A Register
		INX H		Increment the memory pointer
		CMP M		Compare register A and M datas
		JNC L1		If carry jump to loop1
		MOV D, M		Move register M to D
		MOV M,A		Move register M to A
		DCX H		Decrement memory pointer
		MOV M,D		Move register M to D
		INX H		Increment memory pointer
	L1	DCR C		Decrement B register by one
		JNZ L2		Jump if No Zero to loop2
		DCR B		Decrement B register by one
		JNZ L3		Jump if No Zero to loop3
		HLT		Stop

Memory location	Data
9100	
9101	
9102	
9103	
9104	
9105	
9106	
9107	
9108	
9109	

#### Input:

## **Output:**

Memory location	Data
9100	
9101	
9102	
9103	
9104	
9105	
9106	
9107	
9108	
9109	

## **RESULT:**

Thus the program of sort the descending order in given array was executed by using 8085.

#### EX.NO:9

#### Date :

## **PROGRAM FOR CODE CONVERSION – DECIMAL TO HEX**

#### <u>AIM:</u>

To write an assembly language program to convert a given decimal number into hexadecimal number using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Initialize the Memory Pointer.
- 2. Increment B register.
- 3. Increment accumulator by one and adjust to decimal every time.
- 4. Compare the given decimal number with accumulator value.
- 5. When both matches, the equivalent hexadecimal value is in B register.
- 6. Store the resultant in memory location.

#### **FLOWCHART : (DECIMAL TO HEX)**



ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		LXI H,9100		Initialize the memory pointer
		MVI A,00		Clear the Accumulator
		MVI B,00		Clear the B register
	Loop1	INR B		Increment the B register
		ADI 01		Increment the A register
		DAA		Decimal Adjust Accumulator
		CMP M		Compare A and M register
		JNZ Loop1		Jump if No Zero to loop1
		MOV A,B		Move register B to A
		STA 9500		Store the result to memory
		HLT		Stop the program

## Input:

Memory location	Data
9100	

## **Output:**

Memory location	Data
9500	

## **RESULT:**

Thus the program of conversion of decimal to hex given data was executed by using 8085.
# Exp No:10 Date :

### PROGRAM FOR CODE CONVERSION – HEXA DECIMAL TO DECIMAL

# AIM:

To write an assembly language program to convert a given hexadecimal number into decimal number using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Initialize the Memory Pointer.
- 2. Increment B register.
- 3. Increment accumulator by one and adjust to decimal every time.
- 4. Compare the given decimal number with B register value.
- 5. When both match, the equivalent decimal value is in A register.
- 6. Store the resultant in memory location.

#### **FLOWCHART :** (Decimal To Hex)



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ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		LXI H,9100		Initialize the memory pointer
		<i>MVI</i> A,00		Clear the Accumulator
		MVI B,00		Clear the B register
		MVI C,00		Clear the C register
	Loop1	INR B		Increment the B register
		ADI 01		Increment the A register
		DAA		Decimal Adjust Accumulator
		JNC NEXT		If no carry go to next loop
		INR C		Increment register C by one
	NEXT	MOV D,A		Transfer A to D
		MOV A,B		Transfer B to A
		CMP M		Compare A and M register
		MOV A,D		Transfer D to A
		JNZ Loop1		Jump if No Zero to loop1
		STA 9500		Store the result to memory
		MOV A,C		Move register B to A
		STA 9501		Store the result to memory
		HLT		Stop the program

# **PROGRAM:**

# Input:

Memory location	Data
9100	

# **Output:**

Memory location	Data
9500	

# **RESULT:**

Thus the program of conversion of hexadecimal to decimal given data was executed by using 8085.

### EX.NO:11

### **DATE :**

# **PROGRAM FOR CODE CONVERSION – BINARY TO ASCII**

#### <u>AIM:</u>

To write an assembly language program to convert a given binary number into ASCII number using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Start the program
- 2. Load the data from address 9100 to A
- 3. Compare register A and data 0Ah(decimal 10).
- 4. If no carry add 37h with register A.
- 5. If Carry add 30h with register A.
- 6. Store the result to memory location.

**FLOWCHART**: (Binary to ASCII)



ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		LDA 9100		Get the data to Accumulator
		<i>MVI</i> A,00		Clear the Accumulator
		CPI OA		Compare register A and data 10
		JC LOOP1		If carry jump to loop1
		ADI 07H		Add A with 07
	LOOP1	ADI 30H		Add A with 30
		STA 9500		Store the result to memory
		HLT		Stop the program

### **PROGRAM:**

# Input:

Memory location	Data
9100	

# **Output:**

Memory location	Data
9500	

# **RESULT:**

Thus the program of conversion of binary to ASCII given data was executed by using 8085.

# **Exp No : 12**

# DATE :

# PROGRAM FOR CODE CONVERSION - ASCII TO BINARY

#### AIM:

To write an assembly language program to convert a given ASCII number into binary number using 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

### **ALGORITHM:**

- 1. Start the program
- 2. Load the data from address 9100 to A
- 3. Compare register A and data 3Ah.
- 4. If no carry subtract 37h with register A.
- 5. If carry subtract 30h with register A.
- 6. Store the result to memory location.

**FLOWCHART : (ASCII TO BINARY)** 



ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		LDA 9100		Get the data to Accumulator
		<i>MVI</i> A,00		Clear the Accumulator
		CPI 3A		Compare register A and data 3Ah
		JC LOOP1		If carry jump to loop1
		ADI 07H		Add A with 07
	LOOP1	ADI 30H		Add A with 30
		STA 9500		Store the result to memory
		HLT		Stop the program

# **PROGRAM**:

# Input :

Memory location	Data
9100	

# **Output:**

Memory location	Data
9500	

# **RESULT:**

Thus the program of conversion of ASCII to binary given data was executed by using 8085.

# EX.NO:13 DATE :

# PROGRAM FOR INTERFACING OF ADC WITH 8085

#### <u>AIM:</u>

To write an assembly language program to convert an analog signal into a digital signal using an ADC interfacing with 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl. No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1
4	ADC Interfacing kit	1
5	Multimeter	1

#### **Working procedure for ADC:**

- Connect the 5v power supply to trainer kit and adc chord.
- Connect the 26-pin connector from the kit to adc chord.
- Connect the card from keyboard into the socket provided in the kit.
- Switch on the power supply.
- Assemble your program.
- $\blacktriangleright$  Vary the pot in the adc chord.
- Execute it and view the output count in the register A which will be displayed in LCD display.
- Repeat the above steps for different inputs in the pots.

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### 8085 ADDRESS:

8255 contro	l register	address	- 23H
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8255	port A	address	-20H
0255	portri	uuuu	2011

- 8255 port B address -21 H
- 8255 port C address -22H

# **PROGRAM:**

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
9000		MVI A,90		Control Word for port A as input and port c as output
		OUT 23		Out in control RE
		MVI A,01		Select input for MUX
		OUT 21		
		MVI A,FF		
		OUT 22		Port C is enable
		MVI A,00		Start of Conversion(SOC)
		OUT 22		
		MVI A,FF		
		OUT 22		
		CALL 9100		Delay subroutine
		IN20		End of conversion(EOC)
		RST 1		Break point
9100	delay	MVI B,OF		Delay Count
	Loop1	MVI A,FF		Load data FF to register A
	Loop2	NOP		No operation
		NOP		No operation
		DCR A		Decrement register A
		JNZ loop2		If no zero jump to loop2
		DCR B		Decrement register B by one
		JNZ loop1		If no zero jump to loop1
		RET		Return to main Program

Analog Input	Digital output

### **<u>RESULT</u>** :

Thus the conversion of a analog signal into and digital signal was executed using interfacing of ADC with 8085.

# EX.NO:14 DATE :

# **PROGRAM FOR INTERFACING OF DAC WITH 8085**

#### AIM:

To write an assembly language program to convert a digital signal into a analog signal using an DAC interfacing with 8085 microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1
4	DAC Interfacing kit	1
5	CRO	1

#### **Working procedure for DAC:**

- Connect the 5v power supply to trainer kit and dac(0800) chord.
- > Connect the 26-pin connector from the kit to dac(0800) chord.
- > Connect the card from keyboard into the socket provided in the kit.
- Switch on the power supply.
- > Assemble your program. Give the digital data in the software program itself.
- Execute it and view the output count in the register A which will be displayed in CRO
- Repeat the above steps for different digital inputs.

#### i)SQUARE WAVE FORM ALGORITHM:

- 1. Load the initial value (00) to Accumulator and move it to DAC.
- 2. Call the delay program
- 3. Load the final value (FF) to accumulator and move it to DAC.
- 4. Call the delay program.
- 5. Repeat steps 2 to 5.
- 6. Execute the program and using a CRO, verify that the waveform at the DAC2 output is a square-wave. Modify the frequency of the square-wave, by varying the time delay.

#### **8085 ADDRESS:**

8255 control register address	– 23H
8255 port A address	-20H
8255 port B address	-21 H
8255 port C address	-22H

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
9000		MVI A,80		Control Word
		OUT 23		Out in control REG
	LOOP1	MVI A,FF		High Input
		OUT 21		output in port B
		CALL 9100		Delay subroutine
		MVI A,00		Low Input
		OUT 21		output in port B
		CALL 9100		Delay subroutine
		JMP LOOP1(9004)		Jump To Start
9100	delay	MVI C,FF		Delay Count
	Loop1	MVI B,FF		Load data FF to register A
	Loop2	NOP		No operation
		NOP		No operation
		DCR B		Decrement register B
		JNZ loop2		If no zero jump to loop2
		DCR C		Decrement register C by one
		JNZ loop1		If no zero jump to loop1
		RET		Return to main Program

# **PROGRAM: SQUARE WAVE FORM**

# **SQUARE WAVE FORMS**;



time

#### **II) SAW TOOTH GENERATION:**

#### **ALGORITHM:**

- 1. Load the initial value (00) to Accumulator
- 2. Move the accumulator content to DAC.
- 3. Increment the accumulator content by 1.
- 4. Repeat steps 3 and 4.
- 5. Output digital data from 00 to FF constant steps of 01 to DAC1 repeat this sequence again and again. As a result a saw tooth wave will be generated at DAC1 output.

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
9000		MVI A,80		Control Word
		OUT 23		Out in control REG
	START	MVI A,00		Low Input
	LOOP1	OUT 21		output in port B
		INR A		Increment register A by one
		JNZ LOOP1		If zero jump to loop1
		JMP START		Jump To Start

#### **PROGRAM: SAW TOOTH WAVE FORM**

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### **SAW TOOTH WAVE FORM :**



time

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# (iii) TRIANGULAR WAVE GENERATION: ALGORITHMS:

- 1. Load the initial value (00) to Accumulator.
- 2. Move the accumulator content to DAC
- 3. Increment the accumulator content by 1.
- 4. If accumulator content is zero proceed to next step. Else go to step 3.
- 5. Load value (FF) to accumulator.
- 6. Move the accumulator content to DAC.
- 7. Decrement the accumulator content by 1.
- 8. If accumulator content is zero go to step 2. Else go to step 2.

#### **PROGRAM: TRIANGULAR WAVE FORM**

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
9000	START	MVI L,00		Transfer 00 to register L
	LOOP1	MOV A,L		Transfer L to A
		OUT 21		Output in control register
		INR L		Increment register L
		JNZ LOOP1		If no zero jump to loop1
		MVI L,FF		Transfer FF to register L
	LOOP2	MOVA,L		Transfer L to A
		OUT 21		Output in control register
		DCR L		Decrement register L
		JNZ LOOP2		If no zero jump to loop2
		JMP START		Jump to start loop

#### **TRIANGULAR WAVE FORM**:





time

#### **<u>RESULT</u>** :

Thus the conversion of a digital signal into an analog signal was executed using interfacing of DAC with 8085.

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# EXP.No :15

# DATE :

# **PROGRAM FOR KEYBOARD AND DISPLAY INTERFACING WITH 8085**

### AIM:

To interface 8279 Programmable Keyboard Display Controller with 8085 Microprocessor.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1
4	Keyboard and Display Interfacing kit	1

# **PROGRAM: 7 SEGMENT DISPLAY**

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
9000		MVI C,BA		7 segment code for 2
9002		MVI A,12		control word
9004		OUT 71		Control port
9006		MVI A,3E		Frequency division
9008		OUT 71		Control register
900A		MVI A,AO		Display / write inhibit
900C		OUT 71		Control register
900E		MVI B,08		
9010		MVI A,00		Clear display
9012		OUT 70		
9014		DCR B		
9015		JNZ 9012		
9018		MOV A,C		Take the character to display
9019		OUT 70		
901B		JMP 9019		

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Char	D	C	В	Α	Ε	F	G	Н	HEX CODE
0	1	1	1	1	1	1	0	0	FC
1	0	1	1	0	0	0	0	0	60

# **<u>RESULT</u>**:

Thus 8279 controller was interfaced with 8085 and program for rolling display was executed successfully.

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### **EXP.No: 16**

#### DATE :

# PROGRAM FOR INTERFACING - TRAFFIC LIGHT CONTROLLER WITH 8085

#### <u>AIM</u>:

To write an assembly language program to simulate the traffic light at an intersection using a traffic light interface with 8085 microprocessor.

#### **APPARATUS REQUIRED**:

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1
4	Traffic Light control Interfacing kit	1

#### **WORKING PROCEDURE:**

- ➢ Connect the 5V supply to trainer kit.
- ➢ Connect the 26 pin FRC from the kit.
- Switch on the power supply.
- ➢ Assemble the program.
- > Execute it and output display by LED.

#### 8085 ADDRESS:

PORT	ADDRESS
CWR	23
PORT A	20
PORT B	21
PORT C	22

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS		
8500		MAT A 90		All port as output		
8502		MVI A,00		All port as output		
8302	For stor	ting right turn in N S	sidos & pode	estrian stanning		
8504	FOF Star		sides & peut	For pedestrian		
8506		A, 0I		Signal		
8508				For groop I EDg in N S		
8504				Direction		
850C		CALL		Sequence Delay		
830C		DELAY(8569)		Sequence Delay		
850F		CALL		Amber delay		
		AMBER(855F)				
]	For stoppin	ng vehicles in N-S dir	ection & star	ting E-W direction		
8512		MVI A,8B		For stopping N-S sides		
8514		OUT 20		For starting E-W sides		
8516		CALL DELAY		Sequence Delay		
8519		CALL AMBER		Amber delay		
	For star	ting right turn in N-S	5 sides & stop	ping E-W sides		
851C		MVI A,49		For free left in all sides		
851E		OUT 20		For stopping E-W sides		
8520		MVI A,01		For right turn in N-S sides		
8522		OUT 22				
8524		CALL DELAY				
8527		<i>MVI</i> A,07				
8529		OUT 22				
852B		CALL AMBER				
S	topping Ri	ght Turn In N-S Side	s & Starting	Turn In E-W Sides		
852E		MVI A,89				
8530		<i>OUT 20</i>				
8532		<i>MVI</i> A,02				
8534		OUT 22				
8536		CALL DELAY				
8539		MVI A,00				
853B		OUT 22				
853D		MVI A,30				
853F		OUT 20				
8541		MVI C,04				
8543		CALL DELAY				
	For starting Pedestrian					

# **PROGRAM: TRAFFIC LIGHT CONTROLLER**

8546		MVI A,CO	
8548		OUT 20	
854A		MVI A,FO	
854C		OUT 21	
854E		MVI C,10	
8550		CALL DELAYSUB	
8553		MVI A,30	
8555		OUT 20	
8257		MVI C,08	
8259		CALL DELAYSUB	
825C		JMP CONTINUE	
855F	AMBER	MVI A,39	
8561		OUT 20	
8563		MVI C,08	
8568		CALL DELAYSUB	
8568		RET	
8569	DELAY	MVI C,40	
856B		CALL DELAYSUB	
856E		RET	
856F	DELAYSUB		
	BACK2	MVI D,FF	
	BACK1	MVI A,FF	
	BACK	NOP	
		DCR A	
		JNZ BACK	
		DCR D	
		JNZ BACK1	
		MOV A,C	
		JZ OUT	
		DCR C	
		JNZ BACK2	
	OUT	RET	

# **RESULT**:

Thus an assembly language program to simulate the traffic light at an intersection using a traffic light was written and implemented.

# **EXP.No:17**

### DATE:

# PROGRAM FOR I/O PORT SERAIL COMMUNICATION WITH 8085

# AIM:

To write a program to initiate 8251 and to check the transmission and reception of character.

#### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8085 Microprocessor kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1
4	8251/8253 Interfacing kit	1

#### **ALGORITHM:**

- 1. Initialize timer (8253) IC
- 2. Move the Mode command word (36H) to A reg.
- 3. Output it port address CE
- 4. Move the command instruction word (37H) to A reg.
- 5. Output it to port address C8

# **PROGRAM:** SQUARE WAVE GENERATION

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS	
9000		MVI A,36		Channel 0 in mode 3	
		OUT CE		Send mode control word	
		MVI A,0A		LSB of count	
		OUT C8		Write count to register	
		MVI A,00		MSB of count	
		OUT C8		Write count to register	
		HLT		Stop the program	



time

## **<u>RESULT</u>**:

Thus the program to initiate 8251 was written and executed.

# Exp No : 18 Date :

# PROGRAM FOR 8 BIT ADDITION USING 8051

### AIM:

To write an assembly language program for addition of two 8 bit data using 8051 microcontroller.

# **<u>APPARATUS REQUIRED</u>**:

Sl.No	Name of the Apparatus	Qty
1	8051 Microcontroller kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

# **ALGORITHM:**

- 1. Clear the register "C"
- 2. Initialize the memory pointer to data location.
- 3. Get the first Data from memory Location and move to register "A".
- 4. Get the second data from memory location.
- 5. Add first and second data.
- 6. If carry the increment the register 'C' by one.
- 7. Store the result to memory location.

**FLOW CHART:** (8 bit Addition)



# **PROGRAM:**

ADDRESS	LABEL	MNEMONICS	OP CODE	COMMENTS
8000		CLR C		Clear the "Carry" Flag
		MOV R0,#00		
		MOV DPTR,#9200		Initialize the memory pointer
		MOVX A,@DPTR		Move the First Data to A Reg
		MOV B,A		Transfer Data To B
		INC DPTR		Increment the memory pointer
		MOVX A,@DPTR		Get the second data from memory
		ADD A,B		Add First and Second Data
		JNC Loop1		Jump if No Carry to loop1
		INR RO		Increment the "C" register by one
	Loop1	MOV DPTR,#9500		Initialize the memory pointer
		MOVX @DPTR,A		Store The Result
		MOV A,RO		Move the Carry result to Reg "A"
		INC DPTR		Increment the memory pointer
		MOVX @DPTR,A		Store the Carry Result
	HLT	SJMP : HLT		Stop the program

# Input:

Memory location	Data
9200	
9201	

# **Output:**

\_

Memory location	Data
9500	
9501	

# **<u>RESULT</u>** :

Thus the addition of two numbers was performed using the 8085 microprocessor.

# Exp No : 19 Date :

# PROGRAM FOR 8 BIT SUBTRACTION USING 8051

### AIM:

To write an assembly language program for subtraction of two 8 bit data using 8051 microcontroller.

# **<u>APPARATUS REQUIRED</u>:**

Sl.No	Name of the Apparatus	Qty
1	8051 Microcontroller kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

# **ALGORITHM:**

- 1. Initialize the memory pointer to data location.
- 2. Get the first Data from memory and move to register A.
- 3. Get the second data from memory location.
- 4. Subtract the first and second data.
- 5. Store the result to memory location.

### **FLOW CHART:** (8 bit Subtraction)



# **PROGRAM**:

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MOV DPTR,#9200		Initialize the memory pointer
		MOVX A,@DPTR		Move the First Data to A Reg
		MOV B,A		Transfer Data To B
		INC DPTR		Increment the memory pointer
		MOVX A,@DPTR		Get the second data from memory
		SUBB A,B		Add First and Second Data
		MOV DPTR,#9500		Initialize the memory pointer
		MOVX @DPTR,A		Store The Result
	HLT	SJMP : HLT		Stop the program

# Input:

Memory location	Data
9200	
9201	

# **Output:**

Memory location	Data
9500	

# **<u>RESULT</u>** :

-

Thus the subtraction of two numbers was performed using the 8085 microprocessor.

# Exp No: 20 Date :

# PROGRAM FOR 8 BIT MULTIPLICATION USING 8051

### AIM:

To write an assembly language program for multiplication of two 8 bit data using 8051 microcontroller.

#### **<u>APPARATUS REQUIRED</u>:**

Sl.No	Name of the Apparatus	Qty
1	8051 Microcontroller kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

#### **ALGORITHM:**

- 1. Initialize the memory pointer to data location.
- 2. Get the first Data from memory and move to register A.
- 3. Get the second data from memory location.
- 4. Multiply the first and second data.
- 5. Store the result to memory location.

#### **FLOW CHART:** (8 bit Multiplication)



### **PROGRAM:**

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MOV DPTR,#9200		Initialize the memory pointer
		MOVX A,@DPTR		Move the First Data to A Register
		MOV B,A		Transfer Data To B
		INC DPTR		Increment the memory pointer
		MOVX A,@DPTR		Get the second data from memory
		MUL AB		Multiply First and Second Data
		MOV DPTR,#9500		Initialize the memory pointer
		MOVX @DPTR,A		Store The LSB Result
		INC DPTR		Increment the data pointer
		MOV B,A		Transfer B to A
		MOVX @DPTR,A		Store the MSB result
	HLT	SJMP : HLT		Stop the program

# Input:

Memory location	Data
9200	
9201	

### **Output:**

Memory location	Data
9500	
9501	

# **<u>RESULT</u>**:

-

Thus the multiplication of two numbers was performed using the 8085 microprocessor.
## Exp No: 21 Date : PROGRAM FOR 8 BIT DIVISION USING 8051

### <u>AIM</u>:

To write an assembly language program for division of two 8 bit data using 8051 microcontroller.

### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8051 Microcontroller kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1

## **ALGORITHM:**

- 1. Initialize the memory pointer to data location.
- 2. Get the first Data from memory and move to register A.
- 3. Get the second data from memory location.
- 4. Divide the first and second data.
- 5. Store the result to memory location.

**FLOW CHART:** (8 bit Division)



ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000		MOV DPTR,#9200		Initialize the memory pointer
		MOVX A,@DPTR		Move the First Data to A Reg
		MOV B,A		Transfer Data To B
		INC DPTR		Increment the memory pointer
		MOVX A,@DPTR		Get the second data from memory
		DIV AB		Multiply First and Second Data
		MOV DPTR,#9500		Initialize the memory pointer
		MOVX @DPTR,A		Store The Remainder Result
		INC DPTR		Increment the data pointer
		MOV B,A		Transfer B to A
		MOVX @DPTR,A		Store the Quotient result
	HLT	SJMP : HLT		Stop the program

## **PROGRAM**:

## Input:

Memory location	Data
9200	
9201	

## Output:

Memory location	Data
9500	
9501	

# Result:

Thus the division of two numbers was performed using the 8085 microprocessor.

## EX.NO:22 DATE :

## PROGRAM FOR INTERFACING OF ADC WITH 8051

### <u>AIM</u>:

To write an assembly language program to convert an analog signal into a digital signal using an ADC interfacing with 8051 microcontroller.

## **APPARATUS REQUIRED:**

Sl. No	Name of the Apparatus	Qty
1	8051 Microcontroller kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1
4	ADC Interfacing kit	1
5	Multi-meter	1

### **Working procedure for ADC:**

- > Connect the 5v power supply to trainer kit and adc chord.
- Connect the 26-pin connector from the kit to adc chord.
- > Connect the card from keyboard into the socket provided in the kit.
- Switch on the power supply.
- Assemble your program.
- ➢ Vary the pot in the adc chord.
- Execute it and view the output count in the register A which will be displayed in LCD display.
- > Repeat the above steps for different inputs in the pots.

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### **8085 ADDRESS:**

8255 control register address	– 6003H
8255 port A address	-6000H
8255 port B address	-6001 H
8255 port C address	-6002H

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
9000		MOV DPRT,#6003		Control Word for port A as input and port c as output
		MOV A,#90		
		MOVX @DPTR,A		
		MOV DPTR,#6002		
		MOV A,#FF		SOC(start of conversion)
		MOVX @DPTR,A		
		<i>MOV DPRT,#6002</i>		
		MOV A,#00		
		MOVX @DPTR,A		
		MOV DPTR,#6002		
		MOV A,#FF		
		MOVX @DPTR,A		
		LCALL DELAY		
		MOV DPTR,#6000		
		MOV A,#FF		
		MOVX @DPTR,A		
		LCALL 00BB		
	DELAY	MOV R1,#FF		
	LOOP	NOP		
		NOP		
		DJNZ R1,LOOP		
		RET		Return to main Program

Analog Input	Digital output

## **RESULT**:

Thus the conversion of a analog signal into and digital signal was executed using interfacing of ADC with 8051.

## EX.NO:23 DATE :

## PROGRAM FOR INTERFACING OF DAC WITH 8051

## AIM:

To write an assembly language program to convert an digital signal into a analog signal using an DAC interfacing with 8051 microcontroller.

### **APPARATUS REQUIRED:**

Sl.No	Name of the Apparatus	Qty
1	8051 Microcontroller kit	1
2	+5Volts Power Supply	1
3	Keyboard Connector	1
4	DAC Interfacing kit	1
5	CRO	1

#### Working procedure for DAC:

- $\blacktriangleright$  Connect the 5v power supply to trainer kit and dac(0800) chord.
- $\blacktriangleright$  Connect the 26-pin connector from the kit to dac(0800) chord.
- Connect the card from keyboard into the socket provided in the kit.
- Switch on the power supply.
- Assemble your program.
- ➢ Give the digital data in the software program itself.
- Execute it and view the output count in the register A which will be displayed in CRO
- Repeat the above steps for different digital inputs.

#### i)SQUARE WAVE FORM

#### **ALGORITHM:**

- 1. Load the initial value (00) to Accumulator and move it to DAC.
- 2. Call the delay program
- 3. Load the final value (FF) to accumulator and move it to DAC.
- 4. Call the delay program.
- 5. Repeat steps 2 to 5.
- 6. Execute the program and using a CRO, verify that the waveform at the DAC2 output is a square-wave. Modify the frequency of the square-wave, by varying the time delay.

### 8085 ADDRESS:

8255 control register address	- 6003H
8255 port A address	-6000H
8255 port B address	-6001 H
8255 port C address	-6002H

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000	LOOP1	MOV P1,#00		Low Input
		LCALL DELAY		Call Delay
		MOV P1,#99		High Input
		LCALL DELAY		Call Delay
		SJMP START		Jump To Start
	DELAY	MOV R0,#FF		
	RPT	DJNZ R0,RPT		
		RET		Return to main Program

## **PROGRAM: SQUARE WAVE FORM**



time

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## **II) SAW TOOTH GENERATION:**

#### **ALGORITHM:**

- 1. Load the initial value (00) to Accumulator
- 2. Move the accumulator content to DAC.
- 3. Increment the accumulator content by 1.
- 4. Repeat steps 3 and 4.
- 5. Output digital data from 00 to FF constant steps of 01 to DAC1 repeat this sequence again and again. As a result a saw tooth wave will be generated at DAC1 output.

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
9000	LOOP	MOV P1,R1		
		LCALL DELAY		
		INC R1		
		SJMP LOOP		
	DELAY	MOV R0,#FF		
	RPT	DJNZ,R0,RPT		
		RET		

#### **PROGRAM: SAW TOOTH WAVE FORM**



time

## **RESULT :**

Thus the conversion of a digital signal into an analog signal was executed using interfacing of DAC with 8051.

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## EX.NO:24 DATE

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## PROGRAM FOR INTERFACING STEPPER MOTOR USING 8051 MICROCONTROLLER

#### <u>AIM:</u>

To interface a stepper motor with 8051 microcontroller and operate it.

### **THEORY:**

A motor in which the rotor is able to assume only discrete stationary angular position is a stepper motor. The rotary motion occurs in a step-wise manner from one equilibrium position to the next. Stepper Motors are used very wisely in position control systems like printers, disk drives, process control machine tools, etc.

The basic two-phase stepper motor consists of two pairs of stator poles. Each of the four poles has its own winding. The excitation of any one winding generates a North Pole. A South Pole gets induced at the diametrically opposite side. The rotor magnetic system has two end faces. It is a permanent magnet with one face as South Pole and the other as North Pole.

The Stepper Motor windings A1, A2, B1, B2 are cyclically excited with a DC current to run the motor in clockwise direction. By reversing the phase sequence as A1, B2, A2, B1, anticlockwise stepping can be obtained.

#### 2-PHASE SWITCHING SCHEME:

In this scheme, any two adjacent stator windings are energized. The switching scheme is shown in the table given below. This scheme produces more torque.

A1	A2	B1	B2	HEX	CLOCK WISE	ANTI CLOCKWISE
1	0	0	1	09	↓ ↓	<b>↑</b>
0	1	0	1	05		
0	1	1	0	06		
1	0	1	0	0A	1	

### **PROCEDURE**:

- 1. Enter the above program starting from location 4100.and execute the same.
- 2. The stepper motor rotates.
- 3. Varying the count at R4 and R5 can vary the speed.
- 4. Entering the data in the look-up TABLE in the reverse order can vary direction of rotation.

## **PROGRAM:**

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
8000	START	MOV DPTR,#TABLE		Initialize the memory pointer
		MOV R0,#04		Load the counter
	LOOP1	MOVX A,@DPTR		Move the First Data to A Reg
		PUSH DPH		Transfer DPH to SP
		PUSH DPL		Transfer DPL to SP
		MOV		Initialize the port address
		<i>DPTR,#0FFCO</i>		
		MOVX @DPTR,A		Send the value to port address
		MOV R4,#0FF		Delay subroutine
	D1	MOV R5,#0FF		
	D2	DJNZ R5,D2		
		DJNZ R4,D1		
		POP DPL		
		POP DPH		
		INC DPTR		Next data
		SJMP : START		Stop the program
	LOOKUP	09,06,05,0A		Data's

## **RESULT**:

Thus a stepper motor was interfaced with 8051 and run in forward and reverse directions at various speeds.